Autonics

• Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

- Δ symbol indicates caution due to special circumstances in which hazards may occur.
- **Warning** Failure to follow instructions may result in serious injury or death

Safety Considerations

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. **03. Install on a device panel to use.**
- Failure to follow this instruction may result in fire or electric shock.04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire or electric shock. **05. Check 'Connections' before wiring.**
 - Failure to follow this instruction may result in fire.

06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire or electric shock.

- **Caution** Failure to follow instructions may result in injury or product damage
- 01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact failure.

- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire or electric shock.04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Dual Display PID Temperature Controllers



TCN Series PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- Dual digital display (PV/SV)
- 100ms high-speed sampling rate and \pm 0.5% display accuracy
- Switch between relay output and SSR drive output (patent) *
- SSR drive output (SSRP function) control options : ON/OFF control, cycle control, phase control
- Compact design with large display panels for easier reading
- Connector plug types offer easier wiring and maintenance (TCN4S---P)
- *Korea Patent Registration 10-1002582, U.S.A. Patent Registration 8645000, Japan Patent Registration 3184816, China Patent Registration ZL200980111733X, Vietnam Patent Registration 1-0012131, India Patent Registration 291573, Indonesia Patent Registration IDP0032166



Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
- For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- 24 VAC ~ 24-48 VDC≕ power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments. Indoors (in the environment condition rated in 'Specifications') - Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website

0 8 Т С 0 0 6 Ν --

O Digit

4:4 digit

O Power supply

Control output

R: Relav

S: SSR drive

O Wiring type

No mark: Bolt

Ø Size

S: DIN W 48 \times H 48 mm M: DIN W 72 \times H 72 mm H: DIN W 48 \times H 96 mm

L: DIN W 96 \times H 96 mm

Option in/output

2: Alarm 1/2

Product Components

Product (+ bracket)

Instruction manual

P: Connector plug connection

6 2: 24 VAC~ 50/60 Hz, 24-48 VDC== 4: 100-240 VAC \sim 50/60 Hz

Specifications

Series

range

Power supply

Permissible voltage

TCN4 -22 -

24 - 48 VDC=

24 VAC~ 50/60 Hz

90 to 110 % of rated voltage

TCN4 -24 -

100 - 240 VAC~ 50/60 Hz

Power c	onsumption	AC: \leq 5 VA, DC: \leq 3 W \leq 5 VA				
Samplin	g period	100 ms				
Input sp	ecification	Refer to 'Input Type and Using Range.				
Control	Relay	250 VAC~ 3A, 30 VDC= 3A, 1a				
output	SSR	$12 \text{ VDC} = \pm 2 \text{ V}, \le 20 \text{ mA}$				
Alarm o	utput	250 VAC~1 A 1a				
Display	type	7 Segment (red, green), LED type				
Control type	Heating, Cooling	ON/OFF, P, PI, PD, PID Control				
Hysteres	sis	1 to 100 (0.1 to 50.0) °C/°F				
Proporti (P)	ional band	0.1 to 999.9 °C/°F				
Integral	time (I)	0 to 9,999 sec				
Derivati	ve time (D)	0 to 9,999 sec				
Control	cycle (T)	0.5 to 120.0 sec				
Manual	reset	0.0 to 100.0%				
Relay	Mechanical	\geq 5,000,000 operations				
life cycle Electrical		$\begin{array}{l} \text{OUT1/2:} \geq 200,000 \text{ operations} (\text{load resistance: } 250 \text{ VAC} \sim 3 \text{ A}) \\ \text{AL1/2:} \geq 300,000 \text{ operations} (\text{load resistance: } 250 \text{ VAC} \sim 1 \text{ A}) \end{array}$				
Dielectric strength		Between the charging part and the case: 1,000 VAC ~ 50/60 Hz for 1 min Between the charging part and t case: 2,000 VAC ~ 50/60 Hz for 1 min				
Vibratio	n	0.75 mm amplitude at frequency of 5 to 55 Hz in each X, Y, Z direction for 2 hours				
Insulation resistant		≥ 100 MΩ (500 VDC≕ megger)				
Noise in	munity	± 2 kV square shaped noise (pulse width: 1 $\mu s)$ by noise simulator R-phase, S-phase				
Memory	retention	\approx 10 years (non-volatile semiconductor memory type)				
Ambient tempera		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)				
Ambient humidity		35 to 85%RH, storage: 35 to 85%RH	I (no freezing or condensation)			
Insulation type		Mark: , double or reinforced insulation (dielectric strength between the measuring input part and the power part: 1 kV) Mark: , double or reinforced insulation (dielectric strength between the measuring input and the power part: 2 kV)				
Certifica	ition	C E KK • • • • • • • • • • • • • • • • •				
Unit wei	ght	• TCN4S: \approx 100 g (\approx 147 g)	• TCN4M: ≈ 133 g (≈ 203 g)			
(packag		• TCN4H: \approx 124 g (\approx 194 g)	• TCN4L: \approx 179 g (\approx 275 g)			

Sold Separately

• Terminal protection cover: RSA / RMA / RHA / RLA-COVER

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type		Decimal point	Display	Using range (°C)	Using range (°F)
	14 (CA)	1	ЕС Я.Н	-50 to 1,200	-58 to 2,192
	K (CA)	0.1	E C A.L	-50.0 to 999.9	-58.0 to 999.9
		1	JI E.H	-30 to 800	-22 to 1,472
	J (IC)	0.1	JI E.L	-30.0 to 800.0	-22.0 to 999.9
Thermo	L (IC)	1	LIE.H	-40 to 800	-40 to 1,472
-couple		0.1	LI E.L	-40.0 to 800.0	-40.0 to 999.9
	T (CC)	1	E C C.H	-50 to 400	-58 to 752
		0.1	ECC.L	-50.0 to 400.0	-58.0 to 752.0
	R (PR)	1	rPr	0 to 1,700	32 to 3,092
	S (PR)	1	5Pr	0 to 1,700	32 to 3,092
	Cu50 Ω	1	C U 5.H	-50 to 200	-58 to 392
DTD	Cu50 12	0.1	C U 5.L	-50.0 to 200.0	-58.0 to 392.0
RTD		1	dPt.H	-100 to 400	-148 to 752
	DPt100 Ω	0.1	dPt.L	-100.0 to 400.0	-148.0 to 752.0

Display accuracy

Input type	Using temperature	Display accuracy
Thermocouple	At room temperature (23°C ±5 °C)	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or }\pm1\ ^{\circ}\text{C} \text{ higher one}) \pm1\text{-digit} \\ \bullet \text{Thermocouple R, S below 200\ ^{\circ}\text{C}:} \\ (\text{PV}\pm0.5\% \text{ or }\pm3\ ^{\circ}\text{C} \text{ higher one}) \pm1\text{-digit} \\ \text{Over 200\ ^{\circ}\text{C}:} \\ (\text{PV}\pm0.5\% \text{ or }\pm2\ ^{\circ}\text{C} \text{ higher one}) \pm1\text{digit} \\ \bullet \text{Thermocouple L, RTD Cu50\ }\Omega: \\ (\text{PV}\pm0.5\% \text{ or }\pm2\ ^{\circ}\text{C} \text{ higher one}) \pm1\text{-digit} \end{array} $
RTD	Out of room temperature range	(PV ±0.5% or ±2 °C higher one) ±1-digit • Thermocouple R, S below 200 °C: (PV ±1.0% or ±6 °C higher one) ±1digit Over 200 °C: (PV ±0.5% or ±5 °C higher one) ±1digit • Thermocouple L, RTD Cu50 Ω: (PV ±0.5% or ±3 °C higher one) ±1digit

For TCN4S -P, add ±1°C by accuracy standard.
 If the input specification is set to 'decimal point 0.1' display, add ±1°C by accuracy standard.

1 2 3 2 MODE ≪ 📚 🛸

Description

output is ON.

every 1 sec Displays selected unit (parameter).

Turns ON when the alarm

output is ON • CYCLE/PHASE control of

SSR drive output: Turns ON when MV is over 3.0%

Flashes during auto tuning

Turns ON when control

[AC power model]

Unit Descriptions

1. PV Display part (red)

• RUN mode: Displays PV (Present value) • Setting mode: Displays parameter name

2. SV Display part (green)

• RUN mode: Displays SV (Setting value) Setting mode: Displays parameter setting value

4. Input key				
Display	Name			
[MODE]	Mode key			
[◀], [▼], [▲]	Setting value control key			

E	rr	0	rc
-		U	1.5

°C, %, °F

3. Indicator

AL1/2

OUT

AT

Display Name

Alarm

output

Control

output

Auto

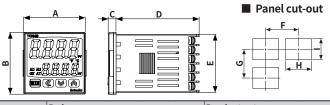
Unit

tuning

	Description	Troubleshooting
oPEn	Flashes when input sensor is disconnected or sensor is not connected.	Check input sensor status.
нннн	Flashes when PV is higher than input range.	When input is within the rated input
LLLL	Flashes when PV is lower than input range.	range, this display disappears.

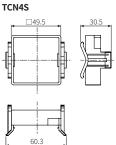
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TCN4S Series .

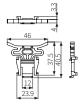


	Body					Panel cut-out			
	A	В	С	D	E	F	G	н	I
TCN4S	48	48	6	64.5	44.8	≥ 65	≥ 65	45+0.5	45+0.5
TCN4S-□-P	48	48	7.7	65.8	44.8	≥ 65	≥ 65	45+0.5	45 ^{+0.5}
TCN4M	72	72	6	64.5	67.5	\geq 90	\geq 90	68+0.7	68 ^{+0.7}
TCN4H	48	96	6	64.5	91.5	≥ 65	≥ 115	45 ^{+0.6}	92 ^{+0.8}
TCN4L	96	96	6	64.5	91.5	≥ 115	≥ 115	92 ^{+0.8}	92 ^{+0.8}

Bracket

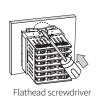


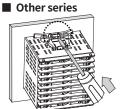
Other series



Installation Method

TCN4S





Flathead screwdriver

Insert the unit into a panel, fasten the bracket by pushing with a flathead screwdriver.

Crimp Terminal Specifications

- Unit: mm, Use the crimp terminal of follow shape.





Wire ferrule

Fork	crimp	terminal
------	-------	----------

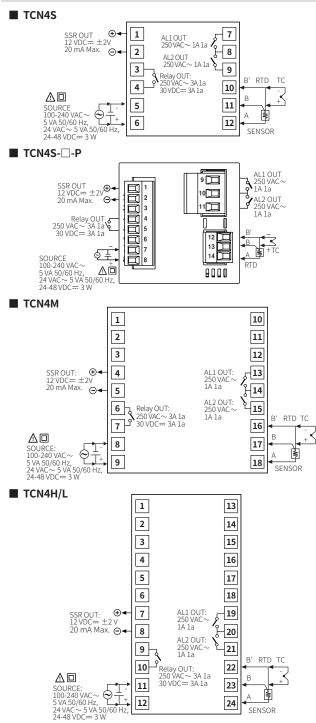
Round crimp terminal

Terminal number	a	b	c
1 to 8	6	≤ 1.7	≤ 3.7
9 to 11	6 to 8	≤ 2.1	≤ 4.2

Terminal number	a	b	c	
1 to 8	6	≤ 1.7	≤ 3.7	
9 to 11	6 to 8	≤ 2.1	≤ 4.2	
12 to 14	6 to 8	≤ 1.5	≤ 3.5	

minal nber	а	b	c	
8	6	≤ 1.7	≤ 3.7	
11	6 to 8	≤ 2.1	≤ 4.2	

Connections

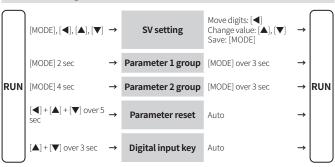


12

24

SENSOR

Mode Setting



Parameter Setting

· Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the description of each item.

• The setting range in parentheses is for using the decimal point display in the input specification.

• If there is no key input for more than 30 seconds in each parameter, it returns to RUN mode.

• When pressing the [MODE] key within 1 second after returning to the operation mode from the parameter group, it will enter the parameter group before returning. • [MODE] key: Saves the current parameter setting value and moves to the next

parameter

[◀] key: Checks the fixed item / Moves the row when changing the set value [▲], [▼] keys: Selects the parameter / Changes the set value

• Recommended parameter setting sequence: Parameter 2 group → Parameter 1 group \rightarrow SV setting mode

Parameter 1 group

-							
Par	ameter	Display	Default	Setting range	Condition		
1-1	AL1 alarm temperature	AL I	1250	Deviation alarm: -F.S. to F.S. °C/°F	2-12/14 alarm		
1-2	AL2 alarm temperature	AL 2	1250	Absolute value alarm: Within input range	operation: AM1 to AM6		
1-3	Auto tuning	ЯĿ	o F F	OFF: Stop, ON: Execution			
1-4	Proportional band	Ρ	0 1 0.0	0.1 to 999.9 °C/°F	2-8 Control		
1-5	Integral time	I	0000	0 (OFF) to 9999 sec	type: PID		
1-6	Derivative time	d	0000	0 (OFF) to 9999 sec			
1-7	Manual reset	rESE	050.0	0.0 to 100.0%	2-8 Control type: PID & 1-5 Integral time: 0		
1-8	Hysteresis	НУ5	002	1 to 100 (0.1 to 50.0) °C/°F	2-8 Control type: ONOF		

Parameter 2 group

_	Parameter	2 5100				
Para	meter	Display	Default	Setting range	Condition	
2-1	Input specification ⁰¹⁾	1 n - E	Ч С Я.Н	Refer to 'Input Type and Using Range'.	-	
2-2	Temperature unit ⁰¹⁾	Unit	٥٢	°C, °F	-	
2-3	Input correction	1 n - 6	0000	-999 to 999 (-199.9 to 999.9) °C/°F	-	
2-4	Input digital filter	⊼Ru.F	000.1	0.1 to 120.0 sec	-	
2-5	SV low limit $^{\scriptscriptstyle (2)}$	L-5u	- 5 0	Within 2-1 Input specification Input	-	
2-6	SV high limit ⁰²⁾	H-5u	1200	range, L-SV ≤ H-SV - 1-digit °C/°F H-SV ≥ L-SV + 1-digit °C/°F	-	
2-7	Control output mode ⁰³⁾	o-FŁ	HERE	HEAT: Heating, COOL: Cooling	-	
2-8	$\operatorname{Control} \operatorname{type}^{^{04)}}$	[-ñd	Pid	PID, ONOF: ON/OFF	-	
2-9	Control output	oUt	гĽУ	RLY: relay, SSR	-	
2-10	SSR drive output type	55r.ñ	Strd	[AC model] STND: standard, CYCL: cycle, PHAS: phase	2-9 Control output: SSR	
2-11	Control cycle	E	2 0.0	0.5 to 120.0 sec	2-9 Control output: RLY 2-10 SSR drive output type: STND	
			2.0		2-9 Control output: SSR 2-10 SSR drive output type: STND	
2-12	AL1 alarm operation	. AL-1	8 ň I.8	AM0: Off AM1: Deviation high limit alarm AM2: Deviation low limit alarm AM3: Deviation high, low limit alarm AM4: Deviation high, low reverse alarm AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm SBA: Sensor break alarm LBA: Loop break alarm (LBA)	-	
2-13	AL1 alarm option			A: Standard alarm D: Alarm latch c: Standby D: Alarm latch and sequence 1 F: Alarm latch and f: Alarm latch and f: Alarm latch and f: Alarm latch and f: Alarm latch and f: Alarm latch and f: Alarm latch	-	
				in 2-12 AL-1 alarm operation.		
2-14	AL2 alarm		A ~ 2.A			
	operation AL2 alarm	AL-5		Same as 2-12/13 AL1 alarm operation/ option	-	
2-15	option			· · · · · · · · · · · · · · · · · · ·		
2-16	Alarm output hysteresis	moutput		2-12/14 AL1/2 alarm operation: AM1 to 6		
2-17	LBA time	L & A.E	0000	0 (OFF) to 9999 sec or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA	
2-18	LBA band	L & A. &	0002	0 (OFF) to 999 (0.0 to 999.9) °C/°F or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA & 2-18 LBA time: > 0	
2-19	Digital input key	91 - F	StoP	STOP: Stop control output, AL.RE: Alarm reset, AT*: Auto tuning execution, OFF	*2-8 Control type: PID	
2-20	Sensor error MV	Er.ñu	000.0	0.0: OFF, 100.0: ON 0.0 to 100.0%	2-8 Control type: ONOF 2-8 Control type: PID	
2-21	Lock	LoC	oFF	OFF LOC1: Parameter 2 group lock LOC2: Parameter 1/2 group lock LOC3: Parameter 1/2 group, SV setting lock	-	

01) Below parameters are initialized when the setting value is changed. - Parameter 1 group: AL1/2 alarm temperature - Parameter 2 group: Input correction, SV high/low limit, Alarm output hysteresis, LBA time, LBA band - SV setting mode: SV

02) If SV is lower than low limit or higher than high limit when the value is changed, SV is changed to the low/high limit value. If 2-1 Input specification is changed, the value is changed to Min./Max. value of Input specification.

03) When the setting value is changed, setting value of 2-20 Sensor error MV is initialized to 0.0 (OFF).
04) When changing the value from PID to ONOF, each value of following parameter is changed.
2-19 Digital input key: OFF, 2-20 Sensor error MV: 0.0 (when setting value is lower than 100.0)

Function: Alarm

<u>888.</u> <u>8</u> Alarm Alarm operation option

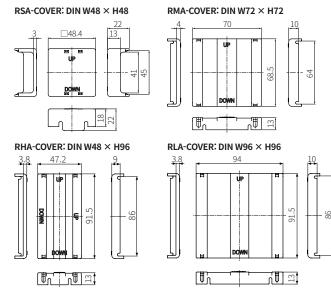
Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

Operation	ation		• H : Alarm ou	Itput hysteresis		
Name	Alarm operation	Description				
-	-		No alarm outp	ut		
Deviation high limit	SV PV 100°C 110°C	H ON PV SV 90°C 100°C deviation: Set as -10°C	If deviation bet SV as high-limit than set value of temperature, th output will be of	t is higher of deviation ne alarm		
Deviation low limit		ON H OFF	If deviation bet and SV as low I than set value o temperature, th output will be 0	imit is higher of deviation ne alarm		
Deviation high, low limit	ON H OFF	H ON A PV 110°C et as 10°C	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.			
Deviation high, low limit reverse	OFF H ON PV SV 90°C 100°C High, Low deviation: Se	H → OFF PV 110°C et as 10°C	If deviation between PV and SV as high/low-limit is lower than set value of deviation temperature, the alarm output will be OFF.			
Absolute value high limit	PV SV 90°C 100°C	PFF H ON SV PV 100°C 110°C ute value: Set as 110°C	If PV is higher than the absolute value, the output will be ON.			
Absolute value low limit	ON H OFF A SV 90°C 100°C Absolute value: Set as 90°C Absolut	ON H → OFF SV PV 100°C 110°C Jte value: Set as 110°C	If PV is lower than the absolute value, the outpu will be ON.			
Sensor break	-		It will be ON when it detects sensor disconnection.			
Loop break	-	It will be ON when it detects loop disconnection.				
Optio	n					
Name	Description			Condition of re-apply		
Standard	If it is an alarm condition, alarm	n output is ON. If it	is a clear alarm			

Name	Description	of re-apply	
Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-	
Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	-	
Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Power ON	
Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second Lalarm condition, alarm latch operates.		
Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm temperature	
Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	/ operation or change STOP to RUN mode	

Sold Separately: Terminal Protection Cover

• Unit: mm



Segment Table

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

7 segment			11	seg	men	ıt	12	seg	men	t	16	seg	men	nt			
٥	0	1	1	٥	0	1	1	٥	0	1	1	٥	0	I	Ι		
1	1	J	J	1	1	Ы	J	1	1	J	J	1	1	Ū	J		
2	2	ĥ	К	2	2	ĸ	К	2	2	К	К	2	2	к	К		
Э	3	L	L	Э	3	L	L	Э	3	L	L	Э	3	L	L		
ч	4	ñ	М	Ч	4	Μ	М	Ч	4	Μ	М	Ч	4	Μ	М		
5	5	n	Ν	5	5	N	N	5	5	N	Ν	S	5	Ν	Ν		
6	6	ο	0	6	6	ο	0	Б	6	ο	0	6	6	۵	0		
7	7	Ρ	Р	Л	7	Ρ	Р	7	7	Ρ	Р	Л	7	Ρ	Ρ		
8	8	9	Q	8	8	۵	Q	8	8	Q	Q	8	8	Q	Q		
9	9	r	R	9	9	R	R	9	9	R	R	9	9	Ŗ	R		
R	A	5	S	Я	А	5	S	Я	А	5	S	R	А	5	S		
Ь	В	Ł	Т	Ь	В	Ł	Т	Ь	В	Ł	Т	3	В	Ţ	Т		
C	С	U	U	٢	С	U	U	C	С	U	U	٢	С	U	U		
d	D	U	V	d	D	V	V	d	D	V	V]]	D	V	V		
Ε	E	Ļ	W	Ε	E	М	W	Ε	E	М	W	Ε	E	н	W		
F	F	5	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х		
G	G	Ч	Y	G	G	Ч	Y	5	G	Ч	Y	6	G	Y	Y		
н	Н	Ξ	Z	н	Н	Z	Z	н	Н	Z	Z	Н	Н	Z	Z		